

Clarification: 5a is still part of HW6, 5 b,c are the extra credit parts.

## .1. deRham Cohomology

Now, let's compute  $H_{\text{deRham}}^*(S^1)$ . Well we know that

$$H^0(S^1) = \mathbb{R}^{\# \text{ connected components}} = \mathbb{R}.$$

How do we compute  $H^1(S^1)$ ? Well recall, we showed that  $H^1(\mathbb{R}) = 0$  by showing that given a closed 1-form, i.e. all 1-forms, then

$$\alpha = d\beta$$

where  $\beta$  is a 0-form on  $\mathbb{R}$  defined by

$$\beta(x) = \int_0^x f(t) dt$$

where  $\alpha = f dx$ .

Now think of  $S^1$  as  $[0, 1]/(0 \sim 1)$ . Then if  $\alpha$  is a 1-form it looks like  $f dx$  where  $dx$  makes sense on  $S^1 = \mathbb{R}/\mathbb{Z}$  since it is invariant under  $x \mapsto x + a$  for all  $a \in \mathbb{R}$  (we only need in  $\mathbb{Z}$ , but this is better).

Moreover, if  $\alpha \in \Omega^1(S^1)$  then  $\alpha = f dx$  where  $f : S^1 \rightarrow \mathbb{R}$  is smooth. Then we should of course take  $\beta : S^1 \rightarrow \mathbb{R}$ , so take

$$\beta(x) = \int_0^x f(t) dt \dots$$

BUT WAIT! We need to know if  $\beta(0) = \beta(1)$ ! This gives us a condition

$$\alpha \text{ is exact} \iff \int_0^1 f(t) dt = 0.$$

We want to look for  $H^1(S^1) = \{\text{closed}\}/\{\text{exact}\}$ . The closed one-forms are just all of them since  $\Omega^2(S^1) = 0$ .

Now let  $\alpha = f(x) dx$  be a closed 1-form. Let  $A := \int_0^1 f(t) dt$ . Then consider  $\alpha - A \cdot dx$ . Then

$$\int_0^1 (f(t) - A) dt = \int_0^1 f(t) dt - A = 0.$$

Thus there exists  $\beta \in \Omega^0(S^1)$  such that  $\alpha - A dx = d\beta$ . Thus  $[\alpha] = [A \cdot dx]$ , which we can think of as  $\mathbb{R}$  since there is one parameter.

Moral: The way the coordinate charts are put together to give you a manifold determines  $H_{\text{dR}}^*(M)$ .

Crucial to put all this together:

### Lemma .1.1 (Poincaré Lemma)

If  $A \subseteq \mathbb{R}^n$  is an open, star-shaped set, then any closed  $k$ -form on  $A$  is exact.

### Definition .1.1

A set  $A \subseteq \mathbb{R}^n$  is called star-shaped provided there exists a point  $p_0 \in A$  (called an observer) such that for any  $p \in A$ , the line segment  $[p_0, p] \in A$ .

Motivation for the Proof:

- This is really a vast generalization of the fundamental theorem of calculus. It is a long calculation.
- In dimension 1 we look at  $g(x) = \int_0^x f(t) dt$  and it turned out  $dg = f(t) dt$ .

- Idea for star-shaped: integrate along segments (i.e. “radially”).

*Proof.* We’ll actually define the following in this proof, called a chain homotopy, the middle maps

$$\begin{array}{ccccc} \Omega^{k-1}(A) & \xrightarrow{d} & \Omega^k(A) & \xrightarrow{d} & \Omega^{k+1}(A) \\ & \nwarrow I_k & & \nwarrow I_{k+1} & \\ \Omega^{k-1}(A) & \xrightarrow{d} & \Omega^k(A) & \xrightarrow{d} & \Omega^{k+1}(A) \end{array}$$

What we want:  $I$  is a linear map,

$$d_{k-1} \circ I_k + I_{k+1} \circ d_k = \text{Id}.$$

Consequence: If  $d\alpha = 0$  for  $\alpha \in \Omega^k(A)$ . Then

$$\alpha = I d\alpha + d(I\alpha) = I(0) + d(I\alpha) = d(I\alpha).$$

Thus we’ll have  $H^*(A) = 0$ . In the one-dimensional case  $I$  was simply integration from 0 to  $x$ . We’ll define  $I_\ell : \Omega^\ell(A) \rightarrow \Omega^{\ell-1}(A)$ . We’ll have

$$\omega = \sum_{i_1 < i_2 < \dots < i_\ell} \omega_I dx_{i_1} \wedge \dots \wedge dx_{i_\ell}$$

where  $\omega_I$  is a smooth function on  $A$  (this works since we’re in  $\mathbb{R}^n$ , so this is true globally, here  $I$  is the index set). We now set

$$(I\omega)(x) := \sum_{i_1 < i_2 < \dots < i_\ell} \sum_{\alpha=1}^{\ell} (-1)^{\alpha-1} \left( \int_0^1 t^{\ell-1} \omega_I(tx) dt \right) \cdot x_{i_\alpha} \cdot dx_{i_1} \wedge \dots \wedge \widehat{dx_{i_\alpha}} \wedge \dots \wedge dx_{i_\ell} \in \Omega^{\ell-1}(A)$$

Without loss of generality here we’ve assumed  $p_0 = 0$  to make things easier to write down. How do we prove this works? I.e. that  $d \circ I + I \circ d = \text{Id}$ . Well, you just write it out...

$$\begin{aligned} d(I\omega) &= \ell \sum_{i_1 < \dots < i_\ell} \left( \int_0^1 t^{\ell-1} \omega_I(tx) dt \right) dx_{i_1} \wedge \dots \wedge dx_{i_\ell} \\ &\quad + \sum_{i_1 < \dots < i_\ell} \sum_{\alpha=1}^{\ell} \sum_{j=1}^n (-1)^{\alpha-1} \left( \int_0^1 t^\ell \frac{\partial \omega}{\partial x_j}(tx) dt \right) x_{i_\alpha} \wedge dx_j \wedge dx_{i_1} \wedge \dots \wedge \widehat{dx_{i_\alpha}} \wedge dx_{i_\ell}. \end{aligned}$$

The first bit is from  $\frac{\partial}{\partial x_{i_\alpha}}$  (and the second bit of product rule), and the  $(-1)^{\alpha-1}$  disappears because we’ve switched it to put it in the right place. The second bit is from  $\frac{\partial}{\partial x_j}$  for any  $j$ , and uses differentiation under the integral sign.

Then we look at  $d\alpha$ . Before we do this, note by linearity it suffices to check equality in a fixed term  $i_1, \dots, i_\ell$ . We’ll suppose  $i_1 = n - \ell + 1, \dots, i_\ell = n$ . So we’ll omit the sum over  $i_1 < \dots < i_\ell$ .

Well this is

$$\begin{aligned} d\omega &= \sum_{j=1}^n \frac{\partial}{\partial x_j} \omega_I dx_j \wedge dx_{i_1} \wedge \dots \wedge dx_{i_\ell} \\ I(d\omega) &= \sum_{j=1}^n \left( \int_0^1 t^\ell \frac{\partial}{\partial x_j} (\omega_1, \dots, i_\ell) dt \right) x_j \widehat{dx_j} \wedge dx_{i_1} \wedge \dots \wedge dx_{i_\ell} \end{aligned}$$

$$- \sum_{\alpha=1}^{\ell} (-1)^{\alpha-1} \left( \int_0^1 t^{\ell} \frac{\partial}{\partial x_j} \omega_I(tx) dt \right) x_{i_{\alpha}} dx_j \wedge dx_{i_1} \wedge \cdots \wedge \widehat{dx_{i_{\alpha}}} \wedge \cdots \wedge dx_{i_{\ell}}.$$

We'll pick up this proof on Friday<sup>1</sup>.

The messy terms then cancel, and we add the other terms

$$\begin{aligned} & \ell \cdot \left( \int_0^1 t^{\ell-1} \omega_I(tx) dt \right) dx_{i_1} \wedge \cdots \wedge dx_{i_{\ell}} + \sum_{j=1}^n \left( \int_0^1 t^{\ell} \frac{\partial}{\partial x_j} \omega_I(tx) dt \right) x_j \cdot dx_{i_1} \wedge \cdots \wedge dx_{i_{\ell}} \\ &= \int_0^1 \frac{d}{dt} (t^{\ell} \omega_I(tx)) dt dx_{i_1} \wedge \cdots \wedge dx_{i_{\ell}} \\ &= \omega_I(x) dx_{i_1} \wedge \cdots \wedge dx_{i_{\ell}} \end{aligned}$$




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<sup>1</sup>The rest of this was technically done on December 2nd