


Lemma .0.1

In a compact Hausdorff space, any two disjoint closed sets can be separated by open neighborhoods which contain these closed sets.

Proof. First we prove that if C is closed and $x \notin C$ then we can separate x, C . We know C is compact since X is compact and Hausdorff. For each $y \in C$, let U_y, V_y separate x, y . Then $\{V_y\}$ covers C , so we can take a finite subcover V_{y_i} . Let $V := \bigcup_i V_{y_i}$ and $U := \bigcap_i U_{y_i}$. U, V clearly separate x, C and are open.

Now take C, C' which are disjoint closed sets. For each $x \in C$, take neighborhoods U_x, V_x separating x, C' . Then by compactness take a finite subcover U_{x_i} . As before union the U_{x_i} and intersect the V_{x_i} to separate C, C' . 


Theorem .0.2

Take X as a topological space with \sim open on X . Then

$$\text{graph } \sim := \Gamma := \{(x, y) \in X \times X \mid x \sim y\}$$


Then X/\sim is Hausdorff if and only if $\Gamma \subseteq X \times X$ is a closed subset.

Proof. Proof of \implies left as an exercise. Suppose $[x] \neq [y]$ within X/\sim . Then $(x, y) \in \Gamma^c$, so using the basis for the product topology, there are U, V open so that $(x, y) \in U \times V$ and $U \times V \subseteq \Gamma^c$.

Thus $\pi(U) \cap \pi(V)$ is empty, where $\pi : X \rightarrow X/\sim$. Furthermore, $\pi(U), \pi(V)$ are open, and so they separate $[x], [y]$. 

Proposition .0.3

If \sim is open, X is second countable, then X/\sim is second countable

Proof Idea. Take a countable basis of X and take their images. These are open, and it's easy to check this is a basis. 

Aside: There is an interesting non-Hausdorff topology. Namely, the closed sets in $\mathbb{R}^n, \mathbb{C}^n$ (some algebraic variety) are given by zeros of polynomials.

Fact: This is compact.

1. Topological Groups/Homogeneous Spaces**Definition .1.1**

We say G is a topological group provided that G is a group equipped with a topology such that the maps

$$\begin{aligned} (g, h) &\mapsto gh \\ g &\mapsto g^{-1} \end{aligned}$$

are continuous as maps $G \times G \rightarrow G$ and $G \rightarrow G$.

Example .1.1

$\mathbb{R}, \mathbb{C}, \mathbb{R}^n, \mathbb{C}^n, \mathbb{Z}, \mathbb{Z}^k$, and any discrete group.

Also $\mathrm{GL}_n(\mathbb{R}), \mathrm{GL}_n(\mathbb{C})$ which are invertible matrices. $O(n)$, the orthogonal group which is the matrices so $A \cdot A^t = I$.

$\mathrm{SO}(n) = \{A \in O(n) \mid \det A = 1\}$, the rotations. Then $\mathrm{SL}_n(\mathbb{R})$ which are the matrices of determinant one.

The circle $S^1 = \mathrm{SO}(2)$. We may also consider $T^n = S^1 \times \cdots \times S^1$, n times and $T^\infty = S^1 \times \cdots \times S^1 \times \cdots$. T^∞ is compact (Tychonoff).

Example .1.2

\mathbb{Q}_p is the completion of \mathbb{Q} with respect to the p -adic norm $\|\cdot\|_p$. Write $a = p^k c, b = p^\ell d$ where c, d are coprime to p , then

$$\left\| \frac{a}{b} \right\|_p = p^{\ell-k}.$$

Note $p^n \rightarrow 0$ as $n \rightarrow \infty$. Furthermore \mathbb{Q}_p is a topological field.

We may look at $\mathrm{SL}(n, \mathbb{Q}_p), \mathrm{GL}(n, \mathbb{Q}_p)$ which have dimension 0.

Definition .1.2

A topological group G is called a Lie group if it is equipped with a smooth differentiable structure such that the maps

$$(g, h) \mapsto gh \qquad g \mapsto g^{-1}$$

are smooth.

Definition .1.3

Let M, N are differentiable manifolds and $f : M \rightarrow N$ is some continuous map. We call f differentiable (C^1, C^k, C^∞ aka smooth) provided that for any coordinate chart $(U_\alpha, \varphi_\alpha)$ around $x \in M$ and any coordinate chart (V_β, ψ_β) around $f(x) \in N$ we have

$$f_{\alpha,\beta} := \psi_\beta \circ f \circ \varphi_\alpha^{-1} : \varphi_\alpha(U_\alpha \cap f^{-1}(V_\beta)) \subseteq \mathbb{R}^{\dim M} \rightarrow \psi_\beta(f(U_\alpha) \cap V_\beta) \subseteq \mathbb{R}^{\dim N}$$

is differentiable (C^1, C^k, C^∞) for all α, β . Notice these sets are nonempty as $x, f(x)$ respectively lie in each of them.

Lemma .1.1

This is well-defined. That is, it is independent of compatible atlases.